Early IR Radiance (L1b) Evaluation

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Early level 1b evaluation will use

- first light data at L+39 days
- first golden day data at L+66 days.
- •Evaluation will focus on

- Radiometric Calibration
- Scan angle effects
- Spectral Calibration
- Spatial Calibration
- Noise evaluation

hha 1 November 01	Earth scene based IR level 1b evaluation between launch+2 and launch+5 months	Concept defined	Initial Prototype evaluation using simulated data documented	Data input requirements documented and availability verified	Sensitivity analysis documente ation complete	Macro ready for real data	Launch+ 3 months Report on first real data	Launch+ 5 months
1. Radiometric C	alibration				Ţ			
	Evaluate during night time warm ocean using (bt2616 - Reynolds.surface.analysis) all scan angles Extremes test. For each channel look at	Hagan			•			
	2% hottest and coldest BT's. Plot trend Radiance Covariance test. Verify that expected covariance agrees with observed.	McMillin McMillin						
	Reflectivity analysis to find channels effected by sun glint	McMillin						
	Radiance Covariance analysis Low temperature radiometry verification using AMSU channels	Strow Strow						
	Evaluate calibration artifacts at array boundaries viewing full footprint deep convective clouds	Aumann						
	Broadband radiometry comparisons using GOES imagers	Tobin						
	Eigenvector analysis of observed radiances to assess information content.	Goldberg						

				Initial					
				Prototype	Data input				
				evaluation	requirements	Sensitivity		Launch+	
				using	documented	analysis		3 months	
		Earth scene based IR level 1b		simulated	and	documente	Macro	Report	Launch+
		evaluation between launch+2 and	Concept	data	availability	ation	ready for	on first	5 months
hha	1 November 01	launch+5 months	defined	documented	verified	complete	real data	real data	Report

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2. Scan angle der	endent calibration accuracy		
	Evaluate (bt2616 - surface.analysis) as		
	function of scan angle during night time		
	warm ocean	Hagan	
	Mirror coating test using <210K scenes.		
	Evaluate as function of scan angle.	McMillin	
	Demonstrate that there is less than 0.2K		
	scan angle asymmetry, using upper		
	tropospheric and stratospheric channels.	Aumann	
3. Spectral Calibr	ation Verification		
	Use accurate RTA (correct frequency).		
	Verify the level 1b provided frequency set		
	is appropriate.	Strow	
	Use accurate RTA (correct frequency) with		
	perturbed SRF's to verify that SRF's in orbit		
	are the same as in RTA.	Strow	
	A simple spectral stability evaluation using		
	channels straddling a line. Trend analysis		
	of the difference.	McMillin	
3. Spatial Calibra	tion Verification		
	Verify IR boresight using coastline		
	crossings	Gregorich	

			Initial Prototype evaluation using	Data input requirements documented	Sensitivity analysis		Launch+ 3 months	
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	evaluation between launch+2 and	Concept	data	availability	ation	ready for	on first	5 months
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ify level1b supplied noise estimates			
ng using the statistics of adjacent			
print differences	Aumann	/hha/index.html	
se evaluation using adjacent footprint			
erence under extended clear conditions			
re than 2 footprints).	McMillin		
luate noise covariance and radiometric			
sstalk.	McMillin		
OT estimation using Earth scene data	Tobin		
luate noise covariance matrix using			
MWF.calculated-observed).clear using			
RTA	Susskind		
	g using the statistics of adjacent print differences e evaluation using adjacent footprint rence under extended clear conditions to than 2 footprints). Luate noise covariance and radiometric stalk. T estimation using Earth scene data luate noise covariance matrix using MVVF.calculated-observed).clear using	g using the statistics of adjacent print differences e evaluation using adjacent footprint rence under extended clear conditions re than 2 footprints). Usate noise covariance and radiometric stalk. T estimation using Earth scene data Usate noise covariance matrix using MVVF.calculated-observed).clear using	g using the statistics of adjacent print differences e evaluation using adjacent footprint rence under extended clear conditions re than 2 footprints). uate noise covariance and radiometric stalk. T estimation using Earth scene data uate noise covariance matrix using MVVF.calculated-observed).clear using

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6. (calc-obs) Bias and stdev	v evaluation:		
for selecte night. Eve frequency moisture a	calculated.ECMWF - observed) ed clear tropical ocean day and aluate bias as function of v, surface temperature, total and scan angle. Evaluate st.dev level 1b provided noise estimate .RTA.	Strow	
clear, nigh Evaluate b surface te	calculated.NCEP - observed) nt for tropical ocean night. bias as function of frequency, emperature, total moisture and e. Use fast RTA.		
bias equa observed)	imple (physical Pathfinder type) tion using (ECMWF.calculated - .clear_using fast RTA using ARM site and global es	Susskind Tobin	
and radial ECMWF t	as between observed radiances nces calculated from NCEP and fields as a function of scan tude bands, day/nite, land type,	Goldberg	

			Initial					
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	evaluation between launch+2 and	Concept	data	availability	ation	ready for	on first	5 months
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7. Other tests:			
	Construct HIRS3 channel radiances from		
	AIRS observations and evaluate using		
	Pathfinder-like retrievals.	Susskind	
	Test clear detection algorithm that has		
	been delivered to JPL (includes predicting		
	2616 from 8 and 11 micron channels,	Goldberg	
	Attempt first set of AIRS/AMSU retrievals		
	using bias corrected radiances and a		
	channel noise covariance matrix	Susskind	
	 Derive first regression coefficients to see if		
	_		
	the radiances.	Goldberg	
	Verify that fixed N2O used for the RTA is		
	appropriate	Strow	
Reference key	ftp://thunder.jpl.nasa.gov/hha/index.html	Aumann	
Reference key	2616 from 8 and 11 micron channels, Attempt first set of AIRS/AMSU retrievals using bias corrected radiances and a channel noise covariance matrix Derive first regression coefficients to see if NCEP model profiles can be derived from the radiances. Verify that fixed N2O used for the RTA is appropriate	Susskind Goldberg Strow	